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3	RESEARCH ARTICLE
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5	MUSCLE ACTIVATION DIFFERS BETWEEN PARTIAL AND FULL BACK
6	SOUAT EXERCISE WITH EXTERNAL LOAD FOUATED
-	SQUAT EXERCISE WITH EXTERIAL LOAD EQUATED
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8	Running title: EMG of dynamic back squat exercise
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28 ABSTRACT

Changes in range of motion affect the magnitude of the load during the squat exercise 29 and, consequently may influence muscle activation. The purpose of this study was to 30 evaluate muscle activation between the partial and full back squat exercise with external 31 load equated on a relative basis between conditions. Fifteen young, healthy, resistance 32 trained men (age: 26±5 years, height: 173±6 cm) performed a back squat at their 10 33 repetition maximum using two different ranges of motion (partial and full) in a 34 randomized, counterbalanced fashion. Surface electromyography was used to measure 35 muscle activation of the vastus lateralis (VL), vastus medialis (VM), rectus femoris 36 37 (RF), biceps femoris (BF), semitendinosus (ST), erector spinae (ES), soleus (SL), and gluteus maximus (GM). In general, muscle activity was highest during the partial back 38 39 squat for GM (P=0.004), BF (P=0.009), and SL (P=0.031) when compared to full. There was no significant difference for RPE between partial and full back squat exercise 40 at 10RM (8 ± 1 and 9 ± 1 , respectively). In conclusion, the range of motion in the back 41 squat alters muscle activation of the prime mover (gluteus maximus), and stabilizers 42 (soleus and biceps femoris) when performed with the load equated on a relative basis. 43 Thus, the partial back squat maximizes the level of muscle activation of the gluteus 44 maximus and associated stabilizer muscles. 45 46

- 47 **Keywords**: exercise, strength, performance.
- 48
- 49

50 **INTRODUCTION**

51 The squat is an exercise that increases hip and knee extensor muscle strength, which in turn can indirectly improve the performance in athletic and non-athletic 52 populations (34). The squat exercise utilizes muscles with different morphology 53 (monoarticular and biarticular), and the muscle forces also vary depending on joint 54 positions (moment arm, length-tension relationship), whether the muscle acts as a prime 55 mover or stabilizer. Though evidence suggests that architecture, position, and function 56 drive muscle performance during the squat, little is known about the neuromuscular 57 changes that occur from a muscle activation standpoint. Elucidating how muscle 58 activation patterns (monoarticular and biarticular) change during the ankle, knee and hip 59 joint movement during squatting at different knee-joint angles would enhance our 60 understanding of how one could capitalize on maximizing muscle activation, and 61 62 improve the exercise prescription in the strength and conditioning areas. Considering the squat exercise is a multi-joint task, a large number of muscle groups are 63 64 simultaneously activated in a complex manner. As a multi-joint exercise, the knee extensors (e.g. rectus femoris, RF; vastus lateralis, VL; and vastus medialis, VM), and 65 hip extensors (e.g. gluteus maximus, GM; biceps femoris, BF; and semitendinosus, ST) 66 are considered to be the prime movers during the squat exercise, with other muscles 67 such as the soleus (SL) and erector spinae (ES) acting in a secondary or stabilizer 68 capacity, respectively (6, 21, 34). Several studies have shown that manipulating features 69 of the squat exercise result in altered muscle activity. These manipulations include 70 changes in foot position (25, 29), barbell position (16), stability of the surface on which 71 the exercise is performed (1, 10, 18, 23, 24), different levels of intensity of load (2), 72 range of motion (2, 6, 20, 32), different equipment (33), and type of contraction 73 (dynamic or isometric) (3, 8, 20). 74

75	The rationale for this study is based on the assumption that the changes in range
76	of motion during the back squat affect the magnitude of the external load that can be
77	used, which may thus affect muscle activation. The external load parameters have been
78	referred in previous studies as body weight (BW) or %BW (6, 7, 9, 26), number of
79	repetition maximum (RM) (7, 15), and percentage of repetition maximum (%1RM)
80	(32). There is a paucity of research comparing muscle activation patterns during
81	different knee angles with the external load equated by the range of motion of the back
82	squat exercise. Therefore, the purpose of this study was to evaluate the muscle
83	activation between partial and full back squat exercise when performed with the load
84	equated on a relative basis.
85	
86	METHODS
87	Experimental Approach to the problem
88	Our study utilized a randomized and counterbalanced design with repeated
<mark>89</mark>	measures to evaluate muscle activation between the partial and full back squat exercise
<mark>90</mark>	with relative external load equated between conditions. All subjects performed a ten
91	repetition maximum (10RM) test equated for each back squat condition (partial and full
92	back squat). The range of motion was determined by an electrogoniometer on the knee
<mark>93</mark>	joint, and all subjects performed both conditions in a self-selected cadence. Surface
<mark>94</mark>	electromyography was measured from the vastus lateralis (VL), vastus medialis (VM),
<mark>95</mark>	rectus femoris (RF), biceps femoris (BF), semitendinosus (ST), erector spinae (ES),
<mark>96</mark>	soleus (SL), and gluteus maximus (GM). All electromyographic data were defined by
<mark>97</mark>	the electrogoniometer data, characterizing both the concentric and eccentric phase of
<mark>98</mark>	each repetition. The rating of perceived exertion (RPE) was evaluated after each back
<mark>99</mark>	squat condition.

100

101 **Subjects** To establish the appropriate sample size for this study, a pilot study was conducted to 102 collect data on the peak sEMG amplitude of the root mean square (RMS) from the VL 103 in both conditions. Based on a statistical power analysis derived from these data (RMS 104 VL EMG), it was determined that twelve subjects would be necessary to achieve an 105 alpha level of 0.05, an effect size of 1.22, and a power $(1-\beta)$ of 0.80 (12). Therefore, we 106 recruited fifteen young, healthy, resistance-trained men (age: 26±5 years, height: 173±6) 107 cm, 10RM test at partial back squat: 92.5±24.9 kg; 10RM test at full back squat: 108 70.9 \pm 23.2 kg and total body mass: 80 \pm 8 kg, 5 \pm 2 years of experience with the back squat 109 exercise) to participate in the study. Subjects had no previous lower back injury, surgery 110 on the lower extremities, and no history of injury with residual symptoms (pain, 111 112 "giving-away" sensations) in the lower limbs within the last year. This study was approved by the University research ethics committee and all subjects read and signed 113 114 an informed consent document (#68/2016). 115 **Procedures** 116 Prior to data collection, subjects were asked to identify their preferred leg for 117

Prior to data collection, subjects were asked to identify their preferred leg for kicking a ball, which was then considered their dominant leg (22). All subjects were right-leg dominant, and the dominant leg was chosen to be analyzed during the squat exercise conditions. Tests were randomized and counterbalanced for all subjects and experimental conditions. Subjects reported to have refrained from performing any lower body exercise other than activities of daily living for at least 48 hours prior to testing. Subjects attended two sessions in the laboratory. During the first session, each subject was instructed in the proper back squat technique for both conditions (partial: 0-

125	90° knee flexion, and full: 0-140° knee flexion). After a subsequent 5-min cycle warm-
126	up at 70 rpm, subjects then performed a ten repetition maximum (10RM) test of the
127	back squat to determine the maximum weight that could be lifted for 10 consecutive
128	repetitions at a self-selected cadence for each condition (partial and full back squat). If a
129	10RM was not achieved in the first attempt, the load was adjusted by 4-10 kg and a
130	minimum five-min rest was given before the next attempt. Only three trials were
131	allowed per testing session in order to avoid neuromuscular fatigue. Subjects received
132	standard instructions regarding technique, and exercise execution was monitored and
133	corrected when necessary to ensure no stopping between eccentric and concentric
134	phases for each test. Verbal encouragement was provided to facilitate optimal
135	performance. After the 10RM load was determined for a given condition, 30 minutes of
136	rest was allowed before the 10RM determination of the alternative condition.
127	The second session was conducted 1 week later and all subjects reported to have
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150 Measures

Surface Electromyography (sEMG): The subjects' body hair was shaved at the site of 151 electrode placement and the skin was cleaned with alcohol before affixing the sEMG 152 electrode. Bipolar active disposable dual Ag/AgCl snap electrodes spanning 1-cm in 153 diameter for each circular conductive area with 2-cm center-to-center spacing were used 154 in all trials. Electrodes were placed on the dominant limb along the axes of the muscle 155 fibers according to the SENIAM/ISEKI protocol (17): Gluteus Maximus (GM) at 50% 156 of the distance between the sacral vertebrae and the greater trochanter; vastus lateralis 157 (VL) at 2/3 of the distance between the anterior spina iliac and the superior aspect of the 158 159 lateral side of the patella; rectus femoris (RF) at 50% on the line from the anterior spina iliac to the superior part of patella; vastus medialis (VM) at 80% on the line between the 160 anterior spina iliac superior and the joint space in front of the anterior border of the 161 162 medial ligament; biceps femoris (BF) at 50% on the line between the ischial tuberosity and the lateral epicondyle of the tibia; and semitendinosus (ST) at 50% on the line 163 164 between the ischial tuberosity and the medial epicondyle of the tibia; erector spinae (ES) at 2 finger width lateral from the process spinae of L1; and soleus (SL) at 2/3 of 165 the line between the medial condylis of the femur to the medial malleolus. The sEMG 166 167 signals were recorded by an electromyographic acquisition system (EMG832C, EMG system Brasil, São José dos Campos, Brazil) with a sampling rate of 2000 Hz using a 168 commercially designed software program (EMG system Brasil, São José dos Campos, 169 170 Brazil). EMG activity was amplified (bi-polar differential amplifier, input impedance = 2M Ω , common mode rejection ratio > 100 dB min (60 Hz), gain x 20, noise > 5 μ V), 171 172 and converted from an analog to digital signal (12 bit). A ground electrode was placed 173 on the right clavicle.

174	EMG signals collected during all conditions were normalized to a maximum
175	voluntary isometric contraction (MVIC) against a fixed strap resistance. Two trials of
<mark>176</mark>	five-second MVICs were performed for each muscle with a one-minute rest interval
177	between actions for the dominant leg. The first MVIC was performed to familiarize the
178	participant with the procedure. For GM MVIC, subjects were in the prone position with
179	their knee flexed at 90° and resistance placed on the distal region of the thigh with the
180	pelvis stabilized. For ES MVIC, subjects were in the prone position with resistance
181	placed on the distal region of the trunk. For VL, VM, and RF MVICs, subjects were
182	seated with their knee flexed at 90° and resistance placed on the distal tibia. For BF and
183	ST MVICs, subjects were seated with their knee flexed at 90° and resistance placed on
184	the distal tibia. For SL MVICs, subjects were seated with their knee flexed at 90° and a
185	vertical resistance placed on the distal femur. Verbal encouragement was given during
186	all MVICs. The order of MVICs was counterbalanced to avoid any potential
187	neuromuscular fatigue.
188	
189	Rating of perceived exertion (RPE): RPE (CR-10 scale) was assessed during each back
190	squat set in both conditions (partial, and full). Standard instructions and anchoring

- 191 procedures were explained during the familiarization session. Subjects were asked to
- use any number on the scale to rate their overall effort for each condition. A rating of 0
- (193) was associated with no effort and a rating of 10 was associated with maximal effort and
- (194) the most stressful exercise ever performed. Subjects were shown the scale 30-min after
- (195) each condition and asked: "How was your workout?"(13).
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199 Data analyses

200	sEMG data were analyzed with a customized Matlab routine (MathWorks Inc.,
201	Massachusetts, USA). All sEMG data were defined by the electrogoniometer data,
202	characterizing both the concentric and eccentric phase of each repetition. The first
203	repetition was removed from the data to ensure anybody adjustment or change in
204	exercise cadence. The digitized sEMG data were band-pass filtered at 20-400 Hz using
205	a fourth-order Butterworth filter with a zero lag. For muscle activation time domain
206	analysis, RMS (150ms moving window) was calculated during the MVIC and the
207	sEMG data. The sEMG data was then normalized to the RMS average of the two peak
208	MVICs for each amplitude and muscle. The RMS analysis was defined from the
209	average of the first three repetitions for each condition and muscle,
210	
211	Statistical Analyses
212	The normality and homogeneity of variances within the data were confirmed by
213	the Shapiro-Wilk and Levene's tests, respectively. A 2x8 repeated-measures ANOVA
214	(condition x muscle) was used to measure differences in RMS. Post-hoc comparisons
215	were performed with the Bonferroni test. Cohen's formula for effect size (d) was
216	calculated, and the results were based on the following criteria: <0.35 trivial effect;
217	0.35-0.80 small effect; 0.80-1.50 moderate effect; and >1.5 large effect, for
218	recreationally trained subjects (31). Interrater reliability was assessed for the researcher
219	who positioned and evaluated RMS tracings for all muscles and conditions. Reliability
220	was operationalized using the following criteria: < 0.4 poor; 0.4 - < 0.75 satisfactory; \geq
221	0.75 excellent. The ICCs ranged between 0.91 and 0.98 (excellent) for all RMS data. An
222	alpha of 5% was used to determine statistical significance.
223	

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- 224 **RESULTS**
- For RMS, there was a significant (P<0.001) main effect for muscles and conditions (P=0.044). The sEMG activity was significantly greater in the partial
- compared to full back squat for the GM (P=0.004, d=1.0, Δ %=29.37), BF (P=0.009,
- 228 d=0.22, Δ %=11.78), and SL (P=0.031, d=0.27, Δ %=10.85) (Figure 1). No significant
- 229 were noted in any of the other muscles studied
- 230 There was no significant difference for RPE between partial and full back squat
- exercise at 10RM (partial: 8 ± 1 and full: 9 ± 1 , P>0.05).
- 232
- 233 *****INSERT FIGURE NEAR HERE*****
- 234 **DISCUSSION**

The purpose of this study was to evaluate the muscle activation between partial and full back squat exercise when performed with the load equated on a relative basis. The main findings of this investigation were that both partial and full back squat demonstrated a similar overall level of muscle activation of the quadriceps femoris, while a higher muscle activation of the gluteus maximus, biceps femoris and erectors spinae was noted in the partial versus full condition.

The squat exercise simultaneously utilizes several muscles with different 241 morphologies (monoarticular and biarticular) in a manner that produces "muscle 242 coordination" (20, 30). A multi-joint task to strengthen the knee and hip extensors is 243 more complex for the neuromuscular system as two joints work in concert to achieve 244 the task (32). Also, since some muscles cross more than one joint, the complexity 245 increases compared to an open chain terminal knee extension or isolated hip extension 246 exercise (32). During the squat exercise, there are several biarticular muscles interacting 247 including the hamstrings and RF (34). Biarticular muscles such as RF, BF and ST have 248

intermediate activation when the muscles have agonistic action at one joint and 249 antagonistic action at the other joint; this is in contrast to the high activation seen when 250 a biarticular muscle works as an agonist for both joints simultaneously (30). Lombard 251 (19) suggested that biarticular muscles of the lower extremity act in a "paradoxical" 252 fashion when the movement is constrained or controlled (named *Lombard's paradox*), it 253 254 is observed with RF, BF, and ST. The extension seen from both the hip and knee is the result of the differential moment arms of the two muscles at each joint and range of 255 motion. The present results showed higher muscle activation for BF in the partial back 256 squat when compared to full condition, which may be explained by the fact that it acts 257 as a joint stabilizer at the knee and a prime mover at the hip. Additionally, the partial 258 back squat presents a longer moment arm at the hip and knee exactly in the sticking 259 region, thereby creating a higher hip and knee extensor moment. Thus, the BF muscle 260 261 allows for the extension of both the knee and hip (32). That said, the absolute activity of the BF was approximately half that of the quadriceps, likely due to the antithetical 262 biarticular actions of the BF during the squat. 263

In comparison to the BF, the RF has a greater moment arm across the knee due 264 to its attachment at the patella, which creates a strong extensor moment at the knee 265 joint. Considering the present results, the RF showed similar muscle activation in both 266 conditions. This may represent a higher effect on muscle activation during the initial 267 phase of the back squat movement (between 20° to 90°) than after 90°, corroborating 268 previous findings by Marchetti et al.(20). Additionally, all muscles may be affected by a 269 sticking point which is considered a poor mechanical force position in which the lengths 270 and mechanical advantages of the muscles involved are such that their capacity to exert 271 force is reduced in this region, and where the lifter experiences difficulty in exerting 272 force against the barbell (11, 35, 37-39). Cardinale et al., (5) displayed that the higher 273

muscle activation during the squat exercise occurs at 90° of knee joint-angle position,
which is considered the sticking region.

During the squat exercise, several monoarticular muscles contribute to 276 movement including the soleus, vasti (lateralis, medialis and intermedius), and GM 277 (34). The present results showed that muscle activation of the VM and VL did not differ 278 between partial and full back squat condition. Additionally, the highest muscle 279 280 activation was observed in the partial condition for GM and SL. When monoarticular muscles perform as agonists, their activation generally increases as the joint moment 281 increases (30). Our findings support this theory as all monoarticular muscles analyzed 282 283 (SL and GM) presented lower values of activation during full back squat. In this specific full position, it is feasible to speculate that changes in muscle length (e.g. GM) 284 and SL) modify muscle contractile abilities and, in turn, modify sEMG-force and 285 286 sEMG-moment relationships (30, 40). Alternatively, afferent signals from muscles could decrease motoneuronal firing frequency (i.e. Golgi tendon reflex) during 287 288 contractions when the muscle fibers are in an elongated position (14). Similar to our results, Robertson et al., (32) reported that the GM muscle activity level was reduced at 289 maximum full (deep-knee) squat depth. Robertson et al., (32) also concluded that the 290 291 biarticular muscles (BF, ST, RF) functioned mainly as stabilizers of the knee and hip 292 joints during the eccentric and concentric phases of a dynamic squat. The authors hypothesized that the reduced GM activity level at maximum squat depth was because 293 the GM was not needed to maintain stability or perhaps that it permitted an extra degree 294 of hip flexion that created a deeper counter-movement immediately before the ascent 295 phase. 296

297

The ankle complex helps to maintain support and balance during squat exercise 298 299 (9, 34). The gastrocnemius has been primarily studied in squat exercise and presents a moderate level of activation (34). On the other hand, the SL is a pure plantar flexor, 300 monoarticular muscle, with an important role mainly in promoting balance in upright 301 tasks. Toutoungi et al. (36) showed that the SL was more active than gastrocnemius at 302 high degrees of knee flexion. The present study observed a lower muscle activation of 303 304 the SL in the full versus partial condition. This may be due to the fact that a higher SL length caused by the full back squat affects the maintenance of balance (e.g. center of 305 pressure) and consequently interferes with sEMG-forces, sEMG-moment relationships 306 307 (30, 40) and afferent signals from Golgi tendon reflex. Others have also investigated muscle activation during the squat by comparing 308 different knee joint angles in the dynamic squat. Caterisano et al., (6) measured the 309 310 relative contributions of GM, BF, VM, and VL muscles of ten experienced lifters while performing dynamic squats at 3 depths (full-depth, the partial, and parallel), using 100-311 312 125% of body weight as resistance. Caterisano et al. (6) found that during the concentric 313 phase of the dynamic squat, the GM activation was higher during full-depth (35.4%) compared to the partial (16.9%) and parallel (28.0%) squat exercise and that the BF, the 314 VM, and the VL did not change. The results suggested that the GM, rather than the BF, 315 the VM, or the VL, becomes more active in concentric contraction as squat depth 316 increases, however, the external load was the same in all conditions, affecting the time 317 under tension and the level of muscle activation. 318 On the other hand, Contreras et al. (7) compared the mean and peak 319 electromyography amplitude of the upper gluteus maximus, lower GM, BF, and VL of 320 front, full, and parallel squats at an estimated 10 RM; no significant differences were 321 seen between full, front and parallel squats for all tested muscles. And, Gorsuch et al., 322

(15) measured the muscle activity during partial and parallel squats at 10 RM. The RF and ES activity were higher during parallel squat than partial squat condition. In the present study, the ES presented high muscle activation during the partial back squat due to the forward trunk inclination aiming to control the center of pressure during the range of motion.

Other studies have shown superior muscular hypertrophy when squatting 328 throughout a full versus a partial range of motion (4, 27). The greater cross-sectional 329 330 area of the muscles found by Bloomquist (4) may be more related to time under tension than the muscle activation. However, without muscle activation data, this remains 331 speculative. Alternatively, the hypertrophic superiority of full squats may be due to 332 training at long muscle lengths, which has been shown to promote greater increases in 333 cross sectional area compared to training at shorter muscle lengths (28). Our study is 334 335 limited by the inclusion of of healthy, well-trained men only, which therefore precludes the genralizability of our findings to other populations. Our sample size was also fairly 336 337 small and the study thus may have been underpowered to identify differences between muscles and conditions. Finally, we did not control for hip and knee angles to create a 338 more realistic squat performance. 339

340

341 PRACTICAL APPLICATION

Performing the back squat at different depths with the load equated on a relative basis alters muscles activation of the prime mover (gluteus maximus), and stabilizers (soleus and biceps femoris). The partial back squat generates the highest muscle activation when compared to full back squat. Alternatively, muscle activation of the knee extensors and knee flexors are unaffected by squat depth.

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461 **FIGURE LEGEND**

Figure 1. Mean and standard deviation of RMS EMG in different back squat conditions
(partial and full). *Means significantly less between amplitudes, *P*<0.05.

